D-90_{DE} Intelligent Multi-sensor Spherical Pod



Characteristics

- Features AI multi-object detection and tracking, which can constantly track one of the persons and vehicles intelligently identified in the image.
- Combination of wide-angle camera and 30x hybrid zoom camera, which can quickly switch between overall and detailed view.
- Laser range finder provides the location of a target and the distance to it.
- Low-profile spherical shape and 3-axis nonorthogonal mechanical stabilized structure, minimize the gyration radius and the wind resistance of the pod. The D-90DE is able to spin continually around its yaw axis.
- With the GCU, the D-90DE supports network, UART and S.BUS control. The GCU supports both private protocol and MAVLink protocol.
- Thanks to the Dual-IMU complementary algorithms with IMU temperature control and carrier AHRS fusion, the D-90DE provides a stabilization accuracy at ±0.01°.
- Can be mounted onto multiple carriers, whether downward or upward.
- With the GCU and the Dragonfly software, user can watch the image and control the pod without protocol ducking.
- Screen supports overlaying OSD information such as latitude, longitude and altitude. Image supports shooting point coordinate EXIF save. Video stream supports SEI stacking.
- 14~53 VDC wide voltage input.

Specifications

| General | | | | | |
|--------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------|--------------------------------|-----------------------------------------------------------------------------------------------------------|--|
| Product Name | D-90 _{DE} | | | | |
| Dimensions | Pod: 96.4 x 96 x 147mm | | | | |
| | GCU: 45.4 x 40 x 13.5mm | | | | |
| Weight | Pod: 576g | | | | |
| | GCU: 18.6g | | | | |
| Operating Voltage | 14 ~ 53 VDC | | | | |
| Power | Pod: 10.5W(AVG, ranging off) / 55W(Stall, ranging on) GCU: 1.8W | | | | |
| Mounting | Downward / Upward | | | | |
| Target Positioning Accuracy ^[1] | Horizonal Error: 1.8 Vertical Error: 0.7m | | @ | Horizonal Distance: 105m Relative Height: 75m | |
| | Horizonal Error: 17 Vertical Error: 6.7m | | @ | Horizonal Distance: 513m Relative Height: 119m | |
| | Horizonal Error: 33 Vertical Error: 13.7r | | @ | Horizonal Distance: 1003m Relative Height: 246m | |
| Gimbal | | | | | |
| Gimbal Type | 3-axis Nonorthogonal Mechanical Stabilization | | | | |
| Angular Accuracy | ±0.01° | | | | |
| Controllable Range | Pitch: -150° \sim +50° , Yaw: $\pm 360^\circ$ constantly | | | | |
| Max Controllable Speed | Pitch: ±200°/s, Yaw: ±200°/s | | | | |
| Zoom Camera | | | | | |
| Image Sensor | 1/2.8" CMOS; Effective Pixels: 2.07M | | | | |
| Lens | Focal Length: $4.7 \sim 47$ mm HFOV: $61.3^{\circ} \sim 6.8^{\circ}$ VFOV: $36.9^{\circ} \sim 3.9^{\circ}$ DFOV: $68.4^{\circ} \sim 7.8^{\circ}$ | | | | |
| Resolution | 1920 x 1080 | | | | |
| Pixel Pitch | 2.9µm | | | | |
| Optical Zoom Rate | 10x | | | | |
| Equivalent Digital Zoom Rate | 3x | | | | |
| Min Illumination | Night Vision off: 0.01Lux / F1.6 Night Vision on: 0.0015Lux / F1.6 | | | | |
| Object Detection Distance | EN62676-4:2015 Johnson Criteria | Person ^[2] : 709 Person: 8103 | 9m; Light veh 8m; Light veh | nicle ^[3] : 932m; Large vehicle ^[4] : 1986m nicle: 24851m; Large vehicle: 52943m | |
| Object Identification Distance | EN62676-4:2015 Johnson Criteria | Person: 2026 | 6m; Light veh | cle: 187m; Large vehicle: 397m iicle: 6213m; Large vehicle: 13236m | |
| Object Verification Distance | EN62676-4:2015 Johnson Criteria | | _ | e: 93m; Large vehicle: 199m iicle: 3106m; Large vehicle: 6618m | |

- [1] Measured by pod mounted on a dual antenna RTK positioned multicopter drone to a known coordinate point. The target positioning accuracy is influenced by carrier's positioning and orientation accuracy, angle between the direction of pod mounted and the heading of carrier, slant range, gradient of measurement line and air quality. The data is for reference only.
- [2] Reference dimension of person: 1.8x0.5m. Critical dimension under Johnson criteria is 0.75m
- [3] Reference dimension of light vehicle: 4.2x1.8m. Critical dimension under Johnson criteria is 2.3m
- [4] Reference dimension of large vehicle: 6.0x4.0m. Critical dimension under Johnson criteria is 4.9m

| Wide Camera | | | | |
|---------------------------------|-----------------------------------------------------------------------|--|--|--|
| Thermal Sensor | 1/2.8" CMOS; Effective Pixels: 2.07M | | | |
| Lens | Focal Length: 5.1mm | | | |
| | HFOV: 71.4° | | | |
| | VFOV: 44.0° | | | |
| | DFOV: 79.6° | | | |
| Resolution | 1920 x 1080 | | | |
| Pixel Pitch | 2.9µm | | | |
| Laser Range Finder | | | | |
| Wavelength | 905nm | | | |
| Max Laser Power | 1mW | | | |
| Beam Angle | 3.5mrad | | | |
| Beam Diameter | 0.35m @ 100m | | | |
| Laser Safety | Class 1M (IEC 60825-1:2014) | | | |
| Measurement Accuracy | ±1.0m | | | |
| Measurement Range | 5-1200m (φ12m vertical surface with 20% reflectivity) | | | |
| AI Multi-object Detection | ፄ Tracking | | | |
| Object Size | 16x16 ~ 128x128 px | | | |
| Object Identification Delay | <40ms | | | |
| Tracking Speed | \pm 32 px / field | | | |
| Tracking Deviation Refresh Rate | 30Hz | | | |
| Tracking Deviation Output Delay | ≤5ms | | | |
| Image & Video | | | | |
| Image Format | JPEG | | | |
| Maximum Image Resolution | 1920 x 1080 | | | |
| EXIF | Shooting point coordinate | | | |
| Video Format | MP4 | | | |
| Maximum Video Resolution | 1080P@25fps | | | |
| Stream Encode Format | H.264, H.265 | | | |
| Stream Network Protocol | RTSP | | | |
| Storage | | | | |
| Supported SD Cards | Supports a Speed Class 10 MicroSD card with a capacity of up to 256GB | | | |
| Support File System | HDD-FAT32 | | | |
| Environment | | | | |
| Operating Temperature | -20°C ~ 50°C | | | |
| Storage Temperature | -40°C ~ 60°C | | | |
| Operating Humidity | ≤85%RH (Non-condensing) | | | |