## D-125AI Intelligent Multi-sensor Spherical Pod



## **Characteristics**

- Features AI multi-object detection and tracking, which can constantly track one of the persons and vehicles intelligently identified in the image.
- Carries an 120x hybrid zoom camera, a thermal camera and a laser range finder.
- Low-profile spherical shape and 3-axis nonorthogonal mechanical stabilized structure, minimize the gyration radius and the wind resistance of the pod. The D-125AI is able to spin continually around its yaw axis.
- Built-in GCU module makes the product more integrated.
- Supports network, UART and S.BUS control. Supports both private protocol and MAVlink protocol.
- Thanks to the Dual-IMU complementary algorithms with IMU temperature control and carrier AHRS fusion, the D-125AI provides a stabilization accuracy at ±0.01°.
- Can be mounted onto multiple carriers, whether downward or upward.
- With the Dragonfly software, user can watch the image and control the pod without protocol ducking.
- Screen supports overlaying OSD information such as latitude, longitude and altitude. Image supports shooting point coordinate EXIF save. Video stream supports SEI stacking.
- 20~53 VDC wide voltage input.

## **Specifications**

General					
Product Name	D-125ai				
Dimensions	142 x 125 x 187mm				
Weight	1055g				
Operating Voltage	20 ~ 53 VDC				
Power	10.7W (Static, ranging off ) / 40.0W (Peak, ranging on )				
Mounting	Downward / Upward				
Target Positioning Accuracy <sup>[1]</sup>	Horizonal Error: 1.8m Vertical Error: 0.7m		@	Horizonal Distance: 105m Relative Height: 75m	
	Horizonal Error: 17.4m Vertical Error: 6.7m		@	Horizonal Distance: 513m Relative Height: 119m	
	Horizonal Error: 33.8m Vertical Error: 13.7m		@	Horizonal Distance: 1003m Relative Height: 246m	
Gimbal					
Gimbal Type	3-axis Nonorthogonal Mechanical Stabilization				
Angular Accuracy	±0.01°				
Controllable Range	Pitch: -120° ~ 40°, F	Roll: ±40°, Yaw:	±360°constant	ly	
Max Controllable Speed	±200°/s				
Zoom Camera					
Image Sensor	1/2.8-inch CMOS, Effective Pixels: 4.09M				
Lens	Actual Focal Length: $4.7 \sim 141$ mm (Equivalent focal length: $27.9 \sim 837$ mm) Aperture: $f/1.5 \sim f/4.0$ HFOV: $59.5^{\circ} \sim 2.2^{\circ}$ VFOV: $35.8^{\circ} \sim 1.2^{\circ}$ DFOV: $66.6^{\circ} \sim 2.5^{\circ}$				
Resolution	2688(H) x 1520(V)				
Pixel Size	2.0μm(H) x 2.0μm(V)				
Optical Zoom Rate	30x				
Equivalent Digital Zoom Rate	4x				
Object Detection Distance	EN62676-4:2015	Person <sup>[2]</sup> : 3283	Bm; Light vehicle	e <sup>[3]</sup> : 4315m; Large vehicle <sup>[4]</sup> : 9192m	
	Johnson Criteria Person: 37500m; Light vehicle: 115000m; Large vehicle: 245000m				
Object Identification Distance	EN62676-4:2015 Person: 657m; Light vehicle: 863m; Large vehicle: 1838m				
	Johnson Criteria Person: 9375m; Light vehicle: 28750m; Large vehicle: 61250m				
Object Verification Distance	EN62676-4:2015 Johnson Criteria		•	.32m; Large vehicle: 919m 14375m; Large vehicle: 30625m	

- [1] Measured by pod mounted on a dual antenna RTK positioned multicopter drone to a known coordinate point. The target positioning accuracy is influenced by carrier's positioning and orientation accuracy, angle between the direction of pod mounted and the heading of carrier, slant range, gradient of measurement line and air quality. The data is for reference only.
- [2] Reference dimension of person: 1.8x0.5m. Critical dimension under Johnson criteria is 0.75m
- [3] Reference dimension of light vehicle: 4.2x1.8m. Critical dimension under Johnson criteria is 2.3m
- [4] Reference dimension of large vehicle: 6.0x4.0m. Critical dimension under Johnson criteria is 4.9m

Thermal Camera				
Thermal Sensor	Uncooled VOy Mis	roholometer		
Lens	Uncooled VOx Microbolometer  Focal Length: 25mm (Equivalent focal length: 93.2mm)  Aperture: f/1.0  HFOV: 17.5°  VFOV: 14.0°  DFOV: 22.3°			
Resolution	640(H) x 512(V)			
Pixel Size	12μm(H) x 12μm(V)			
Spectral Band	8~14µm			
Sensitivity (NETD)	<50mk@F1.0@25℃			
Object Detection Distance		Person: 1042m; Light vehicle: 3194m; Large vehicle:6806m		
Object Identification Distance	Johnson Criteria	Person: 260m; Light vehicle: 799m; Large vehicle: 1701m		
Object Verification Distance		Person: 130m; Light vehicle: 399m; Large vehicle: 851m		
Laser Range Finder				
Wavelength	905nm			
Max Laser Power	1mW			
Beam Angle	2.5mrad			
Beam Diameter	0.25m@100m			
Laser Safety	Class 1M ( IEC 60825-1:2014 )			
Measurement Accuracy	±0.3m (≤300m) / ±1.0m (>300m)			
Measurement Range	5-1800m (φ12m vertical surface with 20% reflectivity)			
AI Multi-object Detection 8	ያ Tracking			
Object Identification Size	≥30x20 px			
Object Identification Rate	≥85%			
Object Identification Quantity	≤50			
Target Tracking Size	16x16~256x256 px			
Tracking Deviation Refresh Rate	30Hz			
Tracking Deviation Output Delay	≤60ms			
Target Pixel Error	≤±1 px			
Tracking Speed	>24 px / frame			
Target Memory Time	>5s			
Image & Video				
Image Format	JPEG			
Maximum Image Resolution	1920 x 1080			
EXIF	Shooting point coordinate			
Video Format	MP4			
Maximum Video Resolution	Stream: 1920 x 1080 @25fps Recording: 1920 x 1080 @30fps			
Stream Encode Format	H.264, H.265			
Stream Network Protocol	RTSP			

Storage	
Supported SD Cards	Supports a Speed Class 10 MicroSD card with a capacity of up to 256GB
Environment	
Operating Temperature	-20°C ~ 50°C
Storage Temperature	-40°C ~ 60°C
Operating Humidity	≤85%RH (Non-condensing)